

Eyr GNSS Receiver

Data Specifications

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|---|---|
| GNSS Signal Tracking¹⁾ | GPS (L1C/A, L1C, L2P(Y), L2C, L5) BDS (B1I, B2I, B3I, B1C, B2a, B2b) GLONASS (L1, L2, L3) Galileo (E1, E5a, E5b, E6) QZSS (L1, L2, L5, L6*) NavIC (L5) SBAS(L1, L2, L5) PPP(B2b-PPP, Galileo E6-HAS) |
| No. of Channels | 1408 |
| POSITIONING PERFORMANCE²⁾ | |
| High-precision static GNSS Surveying Static and Fast Static Post Processing Kinematic (PPK / Stop & Go) | H:2.5 mm + 0.1 ppm RMS / V:3.5 mm + 0.4 ppm RMS H:2.5 mm + 0.5 ppm RMS / V:5 mm + 0.5 ppm RMS H:8mm + 1 ppm RMS / V:15 mm + 1 ppm RMS Initialization time: Typically 10 min for base and 5 min for rover Initialization reliability: Typically >99.9% |
| PPP Code Differential GNSS Positioning Real Time Kinematic (RTK) | H: 10cm / V: 20cm H:±0.25m+1ppm RMS V:±0.5m+1ppm RMS SBAS:0.5m(H) H:8 mm+1ppm RMS / V:15 mm+1 ppm RMS Initialization time: Typically <10 s Initialization reliability: Typically > 99.9% |
| Positioning rate | 1 Hz, 5 Hz and 10 Hz |
| Time to first Fix | Cold start:< 45 s Hot start:< 30 s Signal re-acquisition:< 2 s |
| Tilt Survey Performance³⁾ | Additional horizontal pole-tilt uncertainty typically less than 8 mm +0.7 mm / °tilt (0° ~ 60°) |
| Hi-Fix⁴⁾ | H:RTK+10 mm / minute RMS / V:RTK+20 mm / minute RMS |
| COMMUNICATION Communication | Bluetooth: 4.0 / 2.1+EDR, 2.4 GHz / NFC Wi-Fi: frequency 2.4 GHz, Supports 802.11 b / g / n Frequency: 410-470 MHz Channel: 116 Transmitting power: 0.5 W / 1 W / 2 W adjustable Supports multi-communication protocols: HI-TARGET, TRIMTALK450S, TRIMMARK III, TRANSEOT, SATEL, etc. Working Range: Typically 3~5km, optimal 8~15km |
| Internal UHF Radio | |
| PHYSICAL Internal battery⁵⁾ | Internal 7.2 V / 6900 mAh lithium-ion rechargeable battery. RTK Rover (UHF/Cellular) for 24 hours. Static: up to 24 hours Power consumption: 4.2W Dimensions (W×H): 130mm×79mm Charging:using standard smartphone chargers or external power banks.(Support 5V 2.8A Type-C USB external charging) Weight:≤0.97 kg (includes battery) Data storage:8GB ROM internal storage |
| External power | |
| Control Panel LED Lamp | Satellite, Signal, Power Physical button: 1 |
| Camera Pixel | 2MP&5MP Support real scene stakeout, image measurement, working distance 2~15m |
| Environment Water / Dustproof Shock and vibration | IP68 MIL-STD-810G, Designed to survive a 2 m natural fall onto concrete |
| Humidity Operation temperature Storage temperature | 100%, condensing -40 C ~+75 C -55 C ~+85 C |
| Image Accuracy Image Stakeout Image Measurement | Typically 1cm 2cm~4cm(range 2~15 m) |
| I / O Interface USB type C interface; SMA interface; Nano SIM card slot | |
| Data Formats Output rate Static data format Network model Real Time Kinematic (RTK) Navigation outputs ASCII | 1Hz-20Hz. GNS, Rinex VRS, FKP, MAC; supports NTRIP protocol RTCM 2.x, RTCM 3.x, CRM NMEA-0183 |

*Description and Specifications are subject to change without notice.

[1]QZSS L6 can be provided by firmware upgrade.

[2]The measurement accuracy, precision, reliability and initialization time depend on various factors, including tilt angle, number of satellites, geometric distribution, observation time, atmospheric conditions and multi-path validation, etc. The data are derived under normal conditions.

[3]Regular operations such as rapid rotation and high-intensity vibration may affect the inertial navigation accuracy.

[4]Accuracies are dependent on GNSS satellite availability. Hi-Fix Positioning ends after 5 minutes without differential data.Hi-Fix is not available in all regions, check with your local sales representative for more information.

[5]The battery operating time is related to the operating environment, operating temperature and battery life.

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